

Star product and invariant integration for Lie type noncommutative spacetimes

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ABSTRACT: We present a star product for noncommutative spaces of Lie type, including the so called “canonical” case by introducing a central generator, which is compatible with translations and admits a simple, manageable definition of an invariant integral. A quasi-cyclicity property for the latter is shown to hold, which reduces to exact cyclicity when the adjoint representation of the underlying Lie algebra is traceless. Several explicit examples illuminate the formalism, dealing with κ -Minkowski spacetime and the Heisenberg algebra (“canonical” noncommutative 2-plane).

KEYWORDS: Non-Commutative Geometry, Space-Time Symmetries.

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1. Introduction

The motivation behind noncommutative versions of quantum field theory is by now adequately expounded in the literature. The massive output, in this direction, of the physics-oriented community in the last couple of decades has involved in a substantial way star products, in bewildering numbers, shapes and forms. The present paper adds one more such product in the list, suitable for Lie-type noncommutative spacetimes, and proves several useful properties, using all along explicit examples to clarify the general theorems. What we perceive as virtues for the proposed star product are the following:

- (i) Its definition is natural and easy to compute, eliminating the need for the plethora of *ad hoc* ordering prescriptions other definitions rely on.
- (ii) It coexists harmoniously with translations, in the sense that the corresponding Ω map commutes with them.

- (iii) It admits a simple, manageable definition of a translation-invariant integral — we compute several such integrals explicitly in various examples.
- (iv) The above integral is shown to also satisfy the trace property (cyclicity) for a certain class of underlying Lie algebras, while, in the general case, a simple generalization of the trace property is shown to hold.

On the other hand, the list of truly undesirable features of our star product is, in our mind, currently void. Given this happy state of affairs, we believe it is worth presenting in some detail, in the hope that it might prove useful in physical applications.

As mentioned already, we deal with noncommutative spacetimes of the Lie type, namely, those for which the commutators of the coordinate functions are linear in those same functions. We also adopt a physical point of view, meaning that our reserves of tolerance for the legitimacy of our tools will be considerable, provided they promise to be useful. A natural playground for what is considered here is the κ -Minkowski spacetime, but the also much studied “canonical” noncommutative spacetime fits in our scheme, with minimal modifications — these two constructs form the backdrop of our examples.

The subject we touch upon here is well studied, with several hundred papers published in the general area of deformation quantization during the last three decades. Accordingly, we limit our list of references to only those works that bear a direct relation to ours (and that we know of): refs. [1–7] deal with quantum field theory on noncommutative spacetimes, [8] with noncommutative translations, [9] with symmetry-invariant integration on κ -Minkowski, [10] with coherent state induced star products, [11–15] with more general star product matters and [16–18] with noncommutative differential calculi. On the more mathematical side, refs. [19, 20] deal with star products on the cotangent bundle of a Lie group, their relation to the Kontsevich [21] star product being explored in [22] (see also [23]). Reference [22], along with several others, was brought to our attention by Stefan Waldmann after this paper had essentially been written up — its Lemma 2 establishes the equivalence of ours and Gutt’s star product, although not its explicit form. General arguments then extend the equivalence to include the Kontsevich star product — it is easy to show that our star product does not coincide with any of these two, as both of them deform the product in the direction of the Poisson bracket, while ours only does so for the star commutator (see section 2.2).

Cyclic integrals (trace functionals) for star products are discussed in [24, 25], while KMS functionals for symplectic manifolds are dealt with in [26–28] (see also [29]). The quasi-cyclicity property of our integral seems to be new. Further references to the field can be found in the very extensive list at <http://idefix.physik.uni-freiburg.de/~star/>.

With so much already said on the subject, it is perhaps inevitable that our construction coincides, in particular cases, with choices already made by other authors. Even then though, our general theorems guarantee properties that may have passed unnoticed, and put various approaches in the physics literature under the same, conceptually unifying, roof.

Regarding the structure of the paper, a glance at the table of contents should give an idea of its organization. We point out that some of our proofs make use of Hopf algebra

techniques that might not be familiar to some of the readers. We have opted to present this material separately in an appendix, so as to not disrupt the flow of our presentation.

2. The star product and some of its properties

2.1 Definition of the star product

Consider the N -dimensional Lie algebra \mathfrak{g} with generators \hat{z}_A , $A = 1, \dots, N$, and commutation relations

$$[\hat{z}_A, \hat{z}_B] = \lambda f_{AB}{}^C \hat{z}_C, \quad (2.1)$$

where λ is a formal parameter. We will denote the left invariant vector fields (LIVF) corresponding to \hat{z}_A by Z_A . Expressed in terms of coordinates ζ^A on the corresponding group manifold and the dual partials $\partial_A \equiv \partial/\partial\zeta^A$, they are given by

$$Z_A = \psi_A{}^B(\zeta) \partial_B. \quad (2.2)$$

Evaluated at the identity of the group, Z_A reduces to the partial ∂_A , which implies

$$\epsilon(\psi_A{}^B) = \delta_A{}^B, \quad (2.3)$$

where the *counit* $\epsilon(f(\zeta))$ of a function $f(\zeta)$, is the value of the function at the identity of the group. The $\psi_A{}^B$ also depend on λ . In the limit $\lambda \rightarrow 0$ of an abelian algebra, Z_A also reduces to the partial ∂_A , so that

$$\lim_{\lambda \rightarrow 0} \psi_A{}^B(\zeta) = \delta_A{}^B. \quad (2.4)$$

We use throughout coordinates that vanish at the identity, so that $\epsilon(f(\zeta)) = f(0)$. In the sequel, it will prove convenient to use the notation $z_A \equiv \partial/\partial\zeta^A$ — notice that the \hat{z}_A satisfy the Lie algebra relations, eq. (2.1), while the z_A commute among themselves, like partials do. In this notation,

$$z_A \zeta^B = \delta_A{}^B + \zeta^B z_A, \quad (2.5)$$

and

$$Z_A = \psi_A{}^B(\zeta) z_B. \quad (2.6)$$

We denote by $\tilde{\mathcal{U}}_{\mathfrak{g}}[[\lambda]] \equiv \hat{\mathcal{F}}$ the algebra of formal power series in λ , with coefficients in the (suitably completed) universal enveloping algebra of \mathfrak{g} , and think of it as the (noncommutative) algebra of functions on a quantum space. Similarly, \mathcal{F} will denote formal power series in λ , with coefficients in the algebra of C^∞ functions on \mathbb{R}^N . Our first task is to provide a pair (Ω, \star) , where

$$\Omega: \hat{\mathcal{F}} \rightarrow \mathcal{F} \quad (2.7)$$

is an invertible linear map, and $\star: \mathcal{F} \otimes \mathcal{F} \rightarrow \mathcal{F}$ is a (noncommutative) product between elements of \mathcal{F} , such that

$$\Omega(\hat{f}\hat{g}) = \Omega(\hat{f}) \star \Omega(\hat{g}). \quad (2.8)$$

In the above equation \hat{f} and \hat{g} denote functions of the \hat{z} 's, a convention we use throughout the paper — similarly, symbols like f, g etc. , will denote functions of the z 's. At this point

we introduce a further simplification in the notation, by putting $\Omega(\hat{f}) \equiv f$, in other words, \hat{f} is to be interpreted as $\Omega^{-1}(f)$, and (2.8) becomes

$$\Omega(\hat{f}\hat{g}) = f \star g. \quad (2.9)$$

A final ingredient of our construction is a map ω that applied to a general function $\hat{F}(\zeta, z)$ returns a function of the z 's only, as follows: using the commutation relations (2.5), bring all ζ 's in \hat{F} to the left — denote the resulting expression by

$$\sum_i F_i^{(\bar{1})}(\zeta) F_i^{(2)}(z) \equiv F^{(\bar{1})}(\zeta) F^{(2)}(z) = \hat{F}(\zeta, z). \quad (2.10)$$

Notice the final equality — all we have done with \hat{F} is write it out using a particular ordering. It is also important to keep in mind the suppressed summation in the middle form of the above equation. $\omega(\hat{F})$ is now defined by

$$\omega(\hat{F}(\zeta, z)) = \epsilon(F^{(\bar{1})}(\zeta)) F^{(2)}(z) = F^{(\bar{1})}(0) F^{(2)}(z), \quad (2.11)$$

i.e. , after bringing all ζ 's in \hat{F} to the left, we set them equal to zero — the resulting function of the z 's is $\omega(\hat{F})$ (a similar projection mechanism was used, in a different context, in [30]).

We may now state our definition of $\Omega(\hat{f}(\hat{z}))$:

$$\Omega(\hat{f}(\hat{z})) = \omega(\hat{f}(Z)). \quad (2.12)$$

In a more verbal mood, finding $\Omega(\hat{f}(\hat{z}))$ entails the following procedure

1. Make the substitution $\hat{z}_A \mapsto Z_A = \psi_A^B(\zeta) z_B$ in $\hat{f}(\hat{z})$. Notice that there is no ordering ambiguity involved in this step, given that the Z_A satisfy the same Lie algebra as the \hat{z}_A .
2. In the resulting expression, bring all the ζ 's to the left, using the commutation relations (2.5).
3. Set $\zeta^A = 0$ — the resulting function of the z 's is $\Omega(\hat{f}(\hat{z})) = f(z)$.

The \star -product is now *defined* by (2.9). It should be clear from the above definition, that both Ω and \star depend not only on the Lie algebra \mathfrak{g} , but also on the basis $\{\hat{z}_A\}$ and the choice of coordinates on the group manifold. Still, all properties stated in what follows, hold true in general.

It is interesting that a related, but independent, construction, which, however, does not make use of the LIVFs on the group, is contained in [31] (see also [32]).

2.2 Properties

Proposition 1. *For all \hat{f}, \hat{g} it holds*

$$\omega(\hat{f}(Z)\hat{g}(Z)) = \omega(f(z)\hat{g}(Z)). \quad (2.13)$$

Proof. We have

$$\begin{aligned}\omega(\hat{f}(Z)\hat{g}(Z)) &= \omega(f^{(\bar{1})}(\zeta)f^{(2)}(z)g^{(\bar{1})}(\zeta)g^{(2)}(z)) \\ &= \omega(f^{(\bar{1})}(0)f^{(2)}(z)g^{(\bar{1})}(\zeta)g^{(2)}(z)) \\ &= \omega(f(z)\hat{g}(Z)).\end{aligned}\tag{2.14}$$

In the first equality, we just reordered the ζ 's and z 's in $\hat{f}(Z)$ and $\hat{g}(Z)$ individually. To compute ω , one still needs to commute $g^{(\bar{1})}(\zeta)$ to the left, past $f^{(2)}(z)$ and then set $\zeta = 0$. However, one may already set $\zeta = 0$ in $f^{(\bar{1})}(\zeta)$, since anything with a ζ to its left will eventually vanish, regardless of internal reorderings. The third equality is by definition. \square

Above we have used the notation $\hat{f}(Z) = f^{(\bar{1})}(\zeta)f^{(2)}(z)$, dropping the hat from the f 's in the r.h.s. . This is consistent with (2.10) and the fact that $f^{(\bar{1})}$ and $f^{(2)}$ are both functions of commuting variables. Since Ω is invertible (see below), no ambiguity arises: given an $f(z)$, one can compute $\hat{f}(\hat{z})$, and then $f^{(\bar{1})}(\zeta)f^{(2)}(z)$ as in (2.10).

Proposition 2. Ω is invertible.

Proof. It is easy to see that $\Omega(\hat{z}_{A_1}\hat{z}_{A_2}\dots\hat{z}_{A_n}) = z_{A_1}z_{A_2}\dots z_{A_n} + \mathcal{O}(\lambda)$. Thus, with a suitable ordering of the basis elements in \mathcal{F} , $\hat{\mathcal{F}}$, the matrix of the map Ω is, say, upper triangular, with units along the diagonal and, hence, invertible. \square

Proposition 3. In the notation of (2.10), it holds

$$f(z) \star g(z) = \left(g^{(\bar{1})}(\partial_z) \triangleright f(z)\right) g^{(2)}(z),\tag{2.15}$$

where $\cdot \triangleright \cdot$ denotes the action of a differential operator on a function.

Proof. From (2.5) it can be shown that $f(z)\zeta^A = \partial f(z)/\partial z_A + \zeta^A f(z)$, so that

$$\omega(f(z)\zeta^A) = \frac{\partial f(z)}{\partial z_A},\tag{2.16}$$

and, more generally,

$$\omega(f(z)g(\zeta)h(z)) = (g(\partial_z) \triangleright f(z))h(z),\tag{2.17}$$

where $g(\partial_z)$ is obtained from $g(\zeta)$ by the substitution $\zeta^A \mapsto \partial_{z_A}$ (notice that $h(z)$ above can be taken outside of ω). From (2.13) then we get

$$\begin{aligned}f \star g &= \Omega(\hat{f}(\hat{z})\hat{g}(\hat{z})) \\ &= \omega\left(f(z)g^{(\bar{1})}(\zeta)g^{(2)}(z)\right) \\ &\stackrel{(2.17)}{=} \left(g^{(\bar{1})}(\partial_z) \triangleright f(z)\right) g^{(2)}(z),\end{aligned}\tag{2.18}$$

where we used the equality of left and right actions of partials on functions. \square

Notice that the above star product is \mathfrak{g} -covariant by construction, i.e. , it is bilinear and satisfies $[z_A, z_B]_\star \equiv z_A \star z_B - z_B \star z_A = \lambda f_{AB}^C z_C$. Then, Lemma 2 of [22] implies that it is equivalent to the Gutt star product. It is also worth emphasizing at this point that, in general, we have $z_A \star z_B \neq z_A z_B + \frac{\lambda}{2} f_{AB}^C z_C$, while both the Gutt and Kontsevich constructions satisfy the corresponding equality. Thus, we only deform the commutator in the direction of the Poisson bracket, not the product itself.

2.2.1 Commutativity with translations

The statement of further properties necessitates the introduction of a concept of translation, for both commuting and noncommuting coordinates. In the former case, we formalize the usual $z_A \mapsto z_a + z'_A$ operation via the definition of a *coproduct* map Δ ,

$$\Delta: \mathcal{F} \rightarrow \mathcal{F} \otimes \mathcal{F}, \quad z_A \mapsto z_A \otimes 1 + 1 \otimes z_A, \quad (2.19)$$

extended by linearity and multiplicativity to arbitrary functions in \mathcal{F} ($\alpha, \beta \in \mathbb{R}$),

$$\Delta(\alpha f + \beta g) = \alpha \Delta(f) + \beta \Delta(g), \quad \Delta(fg) = \Delta(f)\Delta(g). \quad (2.20)$$

For noncommuting functions, a similar definition works: the coproduct $\hat{\Delta}$ is given by

$$\hat{\Delta}: \hat{\mathcal{F}} \rightarrow \hat{\mathcal{F}} \otimes \hat{\mathcal{F}}, \quad \hat{z}_A \mapsto \hat{z}_A \otimes 1 + 1 \otimes \hat{z}_A, \quad (2.21)$$

extended again by linearity and multiplicativity to arbitrary functions in $\hat{\mathcal{F}}$. The nontrivial aspect of this definition is that $\hat{\Delta}$ is compatible with the algebra structure, namely,

$$[\hat{\Delta}(\hat{z}_A), \hat{\Delta}(\hat{z}_B)] = \lambda f_{AB}^C \hat{\Delta}(\hat{z}_C), \quad (2.22)$$

where the product in $\hat{\mathcal{F}} \otimes \hat{\mathcal{F}}$ is given by $(\hat{f} \otimes \hat{g})(\hat{h} \otimes \hat{r}) = \hat{f}\hat{h} \otimes \hat{g}\hat{r}$. As can be appreciated already from (2.19), (2.21), the coproduct of a function, commutative or not, involves, in general, a sum over tensor products — the so-called Sweedler notation is standard,

$$\Delta(f) = \sum_i f_{(1)}^i \otimes f_{(2)}^i \equiv f_{(1)} \otimes f_{(2)}, \quad (2.23)$$

and similarly for $\hat{\Delta}(\hat{f})$ (which coproduct is used, Δ or $\hat{\Delta}$, can be inferred from its argument).

We may now state the very important

Proposition 4. *Ω commutes with translations, in the sense that*

$$(\Omega \otimes \Omega)\hat{\Delta}(\hat{f}) = \Delta(\Omega(\hat{f})) = \Delta(f) \quad (2.24)$$

or, in Sweedler notation,

$$\Omega(\hat{f}_{(1)}) \otimes \Omega(\hat{f}_{(2)}) = f_{(1)} \otimes f_{(2)}. \quad (2.25)$$

The proof is given in the appendix. It is worth emphasizing that the \star -product is *not* translation invariant, i.e. , in general,

$$(f \star g)(z + a) \neq f(z + a) \star g(z + a). \quad (2.26)$$

This is due to the fact that the \star -operation involves explicitly the coordinates. One may use the notation \star_z to denote this explicitly, in which case translation invariance holds in the form

$$(f \star_z g)(z + a) = f(z + a) \star_{z+a} g(z + a). \quad (2.27)$$

2.2.2 \star -product homomorphism

Proposition 5. Δ is an algebra homomorphism of the \star -product:

$$\Delta(f \star g) = \Delta(f) \star \Delta(g) \equiv f_{(1)} \star g_{(1)} \otimes f_{(2)} \star g_{(2)}. \quad (2.28)$$

Proof.

$$\begin{aligned} \Delta(f \star g) &\stackrel{(2.9)}{=} \Delta\Omega(\hat{f}\hat{g}) \\ &\stackrel{(2.24)}{=} (\Omega \otimes \Omega)(\hat{\Delta}(\hat{f}\hat{g})) \\ &\stackrel{(2.20)}{=} \Omega\left(\hat{f}_{(1)}\hat{g}_{(1)}\right) \otimes \Omega\left(\hat{f}_{(2)}\hat{g}_{(2)}\right) \\ &\stackrel{(2.9)}{=} f_{(1)} \star g_{(1)} \otimes f_{(2)} \star g_{(2)}. \end{aligned}$$

□

2.2.3 Translation-invariant integration

The above concept of translation for a function $\hat{f}(\hat{z})$ permits the definition of a translation-invariant integral $\llbracket \hat{f}(\hat{z}) \rrbracket$ as follows

$$\llbracket \hat{f}(\hat{z}) \rrbracket \equiv \int_{-\infty}^{\infty} f(z) d^n z \equiv \int f, \quad (2.29)$$

assuming the r.h.s. exists. Translation-invariance is defined and proved in

Proposition 6. $\llbracket \cdot \rrbracket$ is left- and right-invariant, i.e. , it satisfies

$$\llbracket \hat{f} \rrbracket 1 = \hat{f}_{(1)} \llbracket \hat{f}_{(2)} \rrbracket = \llbracket \hat{f}_{(1)} \rrbracket \hat{f}_{(2)}. \quad (2.30)$$

Proof. We prove left invariance, right invariance is proved analogously.

$$\begin{aligned} 1 \llbracket \hat{f} \rrbracket &= 1 \int f \\ &= f_{(1)} \int f_{(2)} \\ &\stackrel{(2.24)}{=} \Omega(\hat{f}_{(1)}) \int \Omega(\hat{f}_{(2)}) \\ &= \Omega(\hat{f}_{(1)}) \llbracket \hat{f}_{(2)} \rrbracket, \end{aligned}$$

where, in the second equality, the translation invariance of the standard integral in \mathbb{R}^N has been used. But $\Omega^{-1}(1) = 1$, so taking Ω^{-1} on both sides we obtain¹

$$1 \llbracket \hat{f} \rrbracket = \hat{f}_{(1)} \llbracket \hat{f}_{(2)} \rrbracket.$$

□

¹Strictly speaking one should differentiate between the unit function $1_{\mathcal{F}}$ and the unit $1_{\mathcal{F}}$.

2.2.4 Quasi-cyclicity property of the integral

Define the constants $c_A \equiv f_{AB}{}^B$.

Proposition 7. $\llbracket \cdot \rrbracket$ satisfies the quasi-cyclicity property

$$\llbracket \hat{f}(\hat{z})\hat{g}(\hat{z}) \rrbracket = \llbracket \hat{g}(\hat{z} + \lambda c)\hat{f}(\hat{z}) \rrbracket. \quad (2.31)$$

The proof is given in the appendix.

Corollary 1. If the adjoint representation of \mathfrak{g} is traceless, $\llbracket \cdot \rrbracket$ is cyclic.

This should be compared to Lemma 3.3 in [24].

Corollary 2. $\llbracket \cdot \rrbracket$ is invariant under the c -number translation $\hat{z}_A \mapsto \hat{z}_A + \lambda c_A$.

Proof. Put $\hat{f} = 1$ in (2.31). □

This last property deserves a comment. The invariance of $\llbracket \cdot \rrbracket$ in the sense of (2.30) can be stated as follows: let \hat{z}' be a second copy of the generators of \mathfrak{g} , satisfying the same Lie algebra, but commuting with the \hat{z} 's. Then

$$\hat{g}(\hat{z} + \hat{z}') = \hat{g}_{(1)}(\hat{z})\hat{g}_{(2)}(\hat{z}'), \quad (2.32)$$

and $\llbracket \hat{g}_{(1)}(\hat{z}) \rrbracket \hat{g}_{(2)}(\hat{z}') = \llbracket \hat{g}(\hat{z}) \rrbracket 1$. But for this property to hold, it is essential that the “translation parameters” \hat{z}' commute with the \hat{z} 's and satisfy the Lie algebra relations among themselves. Yet, the λc 's in Corollary (2), although they do commute with the \hat{z} 's, it would seem that they don't satisfy the Lie algebra relations, being numbers. Or do they? Well, the fact is they do, since $f_{AB}{}^R c_R = 0$, as can be seen starting from the Jacobi identity for the structure constants. Thus, the λc 's are, in some sense, both commuting and noncommuting entities.

3. Examples

3.1 1 + 1 κ -Minkowski spacetime

The 1 + 1 κ -Minkowski algebra is given by

$$[\hat{t}, \hat{x}] = \lambda \hat{x} \quad (3.1)$$

(we use λ , instead of the more usual κ , as deformation parameter). On the corresponding group manifold we use coordinates ξ, τ associated with the representation

$$\rho(g) = \begin{pmatrix} e^{\lambda\tau} & \xi \\ 0 & 1 \end{pmatrix}, \quad (3.2)$$

so that $\epsilon(\xi) = \epsilon(\tau) = 0$. The associated LIVFs are,

$$X = e^{\lambda\tau} x, \quad T = t, \quad (3.3)$$

where $x \equiv \partial_\xi$, $t \equiv \partial_\tau$.

3.1.1 (Ω, \star) for κ -Minkowski

From the above, it is clear that

$$\Omega(\hat{x}^m \hat{t}^n) = \Omega(e^{m\lambda\tau} x^m t^n) = x^m t^n. \quad (3.4)$$

It follows that, for a function $F(x, t) = \sum_i f_i(x) h_i(t)$, we have²

$$\Omega^{-1}(F(x, t)) = \sum_i f_i(\hat{x}) h_i(\hat{t}). \quad (3.5)$$

In particular, putting $r \equiv e^{i(\alpha x + \beta t)}$, we find

$$\hat{r} = \Omega^{-1}(e^{i(\alpha x + \beta t)}) = e^{i\alpha \hat{x}} e^{i\beta \hat{t}}, \quad (3.6)$$

so that

$$\begin{aligned} r^{(\bar{1})} r^{(2)} &\stackrel{(3.6)}{=} e^{i\alpha X} e^{i\beta T} \\ &\stackrel{(3.3)}{=} e^{i\alpha e^{\lambda\tau} x} e^{i\beta t} \\ &= e^{i\alpha(e^{\lambda\tau}-1)x} e^{i(\alpha x + \beta t)} \\ &= \sum_{n=0}^{\infty} \frac{1}{n!} (i\alpha)^n (e^{\lambda\tau} - 1)^n x^n e^{i(\alpha x + \beta t)} \\ &= \sum_{n=0}^{\infty} \frac{1}{n!} (e^{\lambda\tau} - 1)^n x^n \partial_x^n e^{i(\alpha x + \beta t)}, \end{aligned} \quad (3.7)$$

a result that, using linearity, extends to arbitrary functions $h(x, t)$,

$$h^{(\bar{1})}(\xi, \tau) h^{(2)}(x, t) = \sum_{n=0}^{\infty} \frac{1}{n!} (e^{\lambda\tau} - 1)^n x^n \partial_x^n h(x, t). \quad (3.8)$$

Hard as it might look, (3.8) can be summed nicely in an exponential, due to the interesting formula

$$\sum_{n=0}^{\infty} \frac{1}{n!} (e^a - 1)^n z(z-1) \dots (z-(n-1)) = e^{az}, \quad (3.9)$$

the derivation of which is given in the appendix, and the fact that $x^n \partial_x^n = x \partial_x (x \partial_x - 1) \dots (x \partial_x - (n-1))$. Thus, we find

$$h^{(\bar{1})} h^{(2)} = e^{\lambda\tau x \partial_x} \triangleright h, \quad (3.10)$$

and the product $f \star h$ becomes, in standard notation,

$$f \star h = f e^{\lambda \overleftrightarrow{\partial}_t x \overrightarrow{\partial}_x} h. \quad (3.11)$$

²This result coincides with the “time to the right” ordering various authors adopt, see, e.g. , [18].

3.1.2 Invariant integration for κ -Minkowski

Under an integral sign, integration by parts allows us to write (3.11) in the forms

$$\int f \star h = \int \left(e^{-\lambda \partial_t \partial_x x} f \right) h = \int f \left(e^{-\lambda \partial_t x \partial_x} h \right), \quad (3.12)$$

where \int stands for $\iint_{-\infty}^{\infty} dx dt$.

The case where h is a delta function is of particular interest, as it provides a measure of the fuzziness of the \star -product,

$$\bar{f}(x_0, t_0) \equiv \int f(x, t) \star \delta(x - x_0, t - t_0) = \left(e^{-\lambda \partial_t \partial_x x} f \right)(x_0, t_0). \quad (3.13)$$

For $(x_0, t_0) = (0, 0)$, the above expression reduces to

$$\bar{f}(0, 0) = f(0, -\lambda), \quad (3.14)$$

since $(\partial_x x)^n|_{x=0} = (1 + x \partial_x)^n|_{x=0} = 1$, due to the leftmost x in all terms in the binomial expansion except the first one. Notice that, from (3.14), one may *not* deduce that $\bar{f}(x_0, t_0) = f(x_0, t_0 - \lambda)$, as $\int f(x, t) \star \delta(x - x_0, t - t_0) \neq \int f(x + x_0, t + t_0) \star \delta(x, t)$, in general, as mentioned already in the previous section.

Example 1. Invariance and quasi-cyclicity of the integral in κ -Minkowski. The following formulas are easily established and will be useful in what follows

$$g(\hat{t}) \hat{x}^m = \hat{x}^m g(\hat{t} + m\lambda), \quad e^{\alpha \hat{t}} g(\hat{x}) = g(e^{\alpha \lambda} \hat{x}) e^{\alpha \hat{t}}. \quad (3.15)$$

We also compute $c_x = 0$, $c_t = 1$. Consider the function $\hat{F} = e^{\alpha \hat{t}} e^{-\hat{x}^2} e^{-\hat{t}^2}$ with integral

$$\begin{aligned} \llbracket \hat{F} \rrbracket &= \int e^{-e^{2\alpha\lambda} x^2} e^{\alpha t} e^{-t^2} \\ &= \pi e^{\frac{\alpha^2}{4}} e^{-\alpha\lambda}, \end{aligned}$$

and coproduct

$$\Delta(\hat{F}) = \sum_{a=0}^{\infty} \sum_{b=0}^{\infty} \frac{(-2)^a (-2)^b}{(a!)(b!)} \left(e^{\alpha \hat{t}} e^{-\hat{x}^2} \hat{x}^a e^{-\hat{t}^2} \hat{t}^b \otimes e^{\alpha \hat{t}} e^{-\hat{x}^2} \hat{x}^a e^{-\hat{t}^2} \hat{t}^b \right).$$

We compute

$$\begin{aligned} \llbracket \hat{F}_{(1)} \rrbracket \hat{F}_{(2)} &= \sum_{a=0}^{\infty} \sum_{b=0}^{\infty} \frac{(-2)^a (-2)^b}{(a!)(b!)} \llbracket e^{\alpha \hat{t}} e^{-\hat{x}^2} \hat{x}^a e^{-\hat{t}^2} \hat{t}^b \rrbracket e^{\alpha \hat{t}} e^{-\hat{x}^2} \hat{x}^a e^{-\hat{t}^2} \hat{t}^b \\ &= \pi e^{-\alpha\lambda} e^{\alpha \hat{t}} e^{-\hat{x}^2} \left(e^{-2\hat{x}\partial_s} \triangleright e^{\frac{1}{4}s^2} \right)_{s=0} e^{-\hat{t}^2} \left(e^{-2\hat{t}\partial_\alpha} \triangleright e^{\frac{\alpha^2}{4}} \right) \\ &= \pi e^{-\alpha\lambda} e^{\frac{\alpha^2}{4}}, \end{aligned}$$

where we used $\left[\left[e^{\alpha \hat{t}} e^{-\hat{x}^2} \hat{x}^a e^{-\hat{t}^2} \hat{t}^b \right] \right] = \pi e^{-\alpha \lambda} \left(\partial_s^a \triangleright e^{\frac{1}{4}s^2} \right)_{s=0} \left(\partial_\alpha^b \triangleright e^{\frac{\alpha^2}{4}} \right)$. Similarly

$$\begin{aligned} \left[\left[\hat{F}_{(1)} \right] \right] F_{(2)} &= \pi e^{-\alpha \lambda} e^{-e^{2\alpha \lambda} x^2} \left(e^{-2e^{\alpha \lambda} x} \partial_s \triangleright e^{\frac{1}{4}s^2} \right)_{s=0} e^{\alpha t} e^{-t^2} \left(e^{-2t \partial_\alpha} \triangleright e^{\frac{\alpha^2}{4}} \right) \\ &= \pi e^{-\alpha \lambda} e^{\frac{\alpha^2}{4}}. \end{aligned}$$

Therefore, $\left[\left[\hat{F} \right] \right] = \left[\left[\hat{F}_{(1)} \right] \right] \hat{F}_{(2)} = \left[\left[\hat{F}_{(1)} \right] \right] F_{(2)}$. Next, we consider the integral

$$\begin{aligned} \left[\left[\hat{F}(\hat{x} + \lambda c_x, \hat{t} + \lambda c_t) \right] \right] &= \left[\left[e^{\alpha(\hat{t}+\lambda)} e^{-\hat{x}^2} e^{-(\hat{t}+\lambda)^2} \right] \right] \\ &= \int e^{-e^{2\alpha \lambda} x^2} e^{\alpha(t+\lambda)} e^{-(t+\lambda)^2} \\ &= \int e^{-e^{2\alpha \lambda} x^2} e^{\alpha t} e^{-t^2} \\ &= \pi e^{-\alpha \lambda} e^{\frac{\alpha^2}{4}}, \end{aligned}$$

so that $\left[\left[\hat{F}(\hat{z}) \right] \right] = \left[\left[\hat{F}(\hat{z} + \lambda c) \right] \right]$. Finally, we can write $\hat{F} = \hat{f} \hat{g}$ with $\hat{f} = e^{\alpha \hat{t}}$ and $\hat{g} = e^{-\hat{x}^2} e^{-\hat{t}^2}$, and calculate

$$\begin{aligned} \left[\left[\hat{F}(\hat{x}, \hat{t}) \hat{f}(\hat{x} - \lambda c_x, \hat{t} - \lambda c_t) \right] \right] &= \left[\left[e^{-\hat{x}^2} e^{-\hat{t}^2} e^{\alpha(\hat{t}-\lambda)} \right] \right] \\ &= e^{-\alpha \lambda} \int e^{-x^2} e^{-t^2} e^{\alpha t} \\ &= \pi e^{-\alpha \lambda} e^{\frac{\alpha^2}{4}}, \end{aligned}$$

showing that $\left[\left[\hat{f}(\hat{z}) \hat{g}(\hat{z}) \right] \right] = \left[\left[\hat{g}(\hat{z}) \hat{f}(\hat{z} - \lambda c) \right] \right]$. Notice that (3.4) implies that, in this case, $\Omega(\hat{g}(\hat{z} + a)) = g(z + a)$, for a a number, so that the star product version of (2.31) is

$$\int f(z) \star g(z) = \int g(z + \lambda c) \star f(z). \quad (3.16)$$

3.1.3 δ_λ for κ -Minkowski

It is interesting to ponder whether there exists an object $\delta_\lambda(x, t; x_0, t_0)$ such that

$$\int f(x, t) \star \delta_\lambda(x, t; x_0, t_0) = f(x_0, t_0). \quad (3.17)$$

Notice that we have carefully refrained from assuming that δ_λ only depends on differences of its arguments. Using the second form of (3.12) in (3.17) we get

$$\delta_\lambda(x, t; x_0, t_0) = e^{\lambda \partial_t x \partial_x} \delta(x - x_0, t - t_0). \quad (3.18)$$

3.2 The Heisenberg algebra (“canonical” NC plane)

The Heisenberg algebra is a three-dimensional real Lie algebra with only nonzero commutator given by

$$[\hat{x}, \hat{z}] = \lambda \hat{y}. \quad (3.19)$$

Notice that, since \hat{y} is central, we are dealing essentially with the so-called “canonical” NC 2-plane. On the Heisenberg group manifold we use coordinates ξ, ψ, ζ , associated with the representation

$$\rho(g) = \begin{pmatrix} 1 & \xi & \psi \\ 0 & 1 & \zeta \\ 0 & 0 & 1 \end{pmatrix}, \quad (3.20)$$

so that $\epsilon(\xi) = \epsilon(\psi) = \epsilon(\zeta) = 0$. The associated LIVFs are,

$$X = x, \quad Y = y, \quad Z = z + \lambda \xi y, \quad (3.21)$$

where $x \equiv \partial_\xi, y \equiv \partial_\psi, z \equiv \partial_\zeta$. It is clear that

$$\Omega(\hat{z}^m \hat{y}^n \hat{x}^k) = \Omega((z + \lambda \xi y)^m y^n x^k) = z^m y^n x^k. \quad (3.22)$$

It follows that, for a function $F(x, y, z) = \sum_i f_i(z) h_i(y) s_i(x)$, we have

$$\Omega^{-1}(F(x, y, z)) = \sum_i f_i(\hat{z}) h_i(\hat{y}) s_i(\hat{x}). \quad (3.23)$$

In particular, with $r \equiv e^{i(\alpha x + \beta y + \gamma z)}$, we find

$$\hat{r} = \Omega^{-1}(e^{i(\alpha x + \beta y + \gamma z)}) = e^{i\gamma \hat{z}} e^{i\beta \hat{y}} e^{i\alpha \hat{x}}, \quad (3.24)$$

so that

$$\begin{aligned} r^{(\bar{1})} r^{(2)} &\stackrel{(3.24)}{=} e^{i\gamma(z + \lambda \xi y)} e^{i\beta y} e^{i\alpha x} \\ &= e^{i\gamma \lambda \xi y} e^{i(\alpha x + \beta y + \gamma z)} \\ &= \sum_{n=0}^{\infty} \frac{\lambda^n}{n!} \xi^n y^n \partial_z^n e^{i(\alpha x + \beta y + \gamma z)}, \end{aligned} \quad (3.25)$$

a result that, by linearity, extends to arbitrary functions $h(x, y, z)$,

$$h^{(\bar{1})}(\xi, \psi, \zeta) h^{(2)}(x, y, z) = \sum_{n=0}^{\infty} \frac{\lambda^n}{n!} \xi^n y^n \partial_z^n h(x, y, z). \quad (3.26)$$

For the product $f \star h$ we find

$$f \star h = (h^{(\bar{1})}(\partial) \triangleright f) h^{(2)} \stackrel{(3.26)}{=} \sum_{n=0}^{\infty} \frac{\lambda^n}{n!} y^n (\partial_x^n f) = f e^{\lambda y \overleftarrow{\partial}_x \overrightarrow{\partial}_z} h, \quad (3.27)$$

which gives, in particular, $x \star z = xz + \lambda y$, $z \star x = zx$, so that $[x, z]_\star = \lambda y$.

Under an integral sign we may use integration by parts to get

$$\int f \star h = \int \sum_{n=0}^{\infty} \frac{1}{n!} (-\lambda)^n y^n (\partial_x^n \partial_z^n f) h = \int \left(e^{-\lambda y \partial_x \partial_z} f \right) h, \quad (3.28)$$

where \int stands for $\iiint_{-\infty}^{\infty} dx dy dz$.

For h equal to a delta function we compute,

$$\bar{f}(x_0, y_0, z_0) \equiv \int f(x, y, z) \star \delta(x - x_0, y - y_0, z - z_0) = \left(e^{-\lambda y \partial_x \partial_z} f \right) (x_0, y_0, z_0). \quad (3.29)$$

For $y_0 = 0$, the above expression reduces to

$$\bar{f}(x_0, 0, z_0) = f(x_0, 0, z_0). \quad (3.30)$$

It is interesting to check the quasi-cyclicity property of the integral, eq. (2.31), in this case. We find that the constants c_A of Proposition 2.2.4 are zero, so that the integral is cyclic. Using (2.15), we compute

$$\int \delta(x - x_0, y - y_0, z - z_0) \star e^{-(x^2 + y^2 + z^2)/2} = \left(e^{\lambda y z \partial_x - \frac{\lambda^2}{2} y^2 \partial_x^2} \triangleright e^{-(x^2 + y^2 + z^2)/2} \right) (x_0, y_0, z_0), \quad (3.31)$$

which, by cyclicity, should be equal to the r.h.s. of (3.29), with f equal to the gaussian. Switching to quantum harmonic oscillator notation, $a_z = (\partial_z + z)/\sqrt{2}$, $a_z^\dagger = (-\partial_z + z)/\sqrt{2}$, and recognizing the gaussian as the ground state wavefunction, we find

$$\begin{aligned} e^{\frac{\lambda}{\sqrt{2}} y \partial_x a_z^\dagger} e^{-\frac{\lambda}{\sqrt{2}} y \partial_x a_z} |0\rangle &= e^{\frac{\lambda}{\sqrt{2}} y \partial_x a_z^\dagger} e^{\frac{\lambda}{\sqrt{2}} y \partial_x a_z} |0\rangle \\ &= e^{\lambda y z \partial_x - \frac{\lambda^2}{4} y^2 \partial_x^2} |0\rangle, \end{aligned} \quad (3.32)$$

where, in the first equality, the sign of a_z can be changed freely, as it annihilates the ground state, while the second follows from the Baker-Cambell-Hausdorff (BCH) formula. On the other hand,

$$e^{\frac{\lambda}{\sqrt{2}} y \partial_x a_z^\dagger} e^{-\frac{\lambda}{\sqrt{2}} y \partial_x a_z} = e^{-\lambda y \partial_x \partial_z + \frac{\lambda^2}{4} y^2 \partial_x^2},$$

by direct application of the BCH formula, so that, comparing with (3.32),

$$e^{\lambda y z \partial_x - \frac{\lambda^2}{4} y^2 \partial_x^2} |0\rangle = e^{-\lambda y \partial_x \partial_z + \frac{\lambda^2}{4} y^2 \partial_x^2} |0\rangle, \quad (3.33)$$

from which the desired equality follows.

For δ_λ we find

$$\delta_\lambda(x, y, z; x_0, y_0, z_0) = e^{\lambda y \partial_x \partial_z} \delta(x - x_0, y - y_0, z - z_0). \quad (3.34)$$

It is clear that in the above formulas the variable y may be given consistently a numerical value, as ∂_y appears nowhere. Thus, by setting, e.g. , $y = 1$, one obtains $[x, z]_\star = \lambda$, i.e. , the “canonical” NC 2-plane. One may effect this substitution, bearing in mind that y can be reinstated in any expression by letting $\lambda \mapsto \lambda y$. Eq. (3.34) shows that, for fixed y , $\delta_\lambda(x, z; x_0, z_0)$ only depends on the differences $x - x_0$, $z - z_0$.

4. Concluding remarks

We have presented a star product for Lie-type noncommutative spacetimes, the corresponding Ω -map, and a translation-invariant and quasi-cyclic integral, along with examples drawn

from κ -Minkowski and canonical noncommutative spacetimes. A natural continuation of our work would be the development of applications to quantum field theory, as in, for example, ref. [5] — this we defer to a future publication. Interesting technical questions that should also be addressed include:

- The implementation in the formalism of symmetries, in particular, Poincaré covariance, perhaps appropriately deformed.
- The study of the transformation properties of the integral $\llbracket \cdot \rrbracket$ under the above symmetry operations.
- Analytical issues associated to the pseudodifferential operators encountered.
- The structure of the Ω -map, and the determination of the explicit form of the equivalence with Gutt's and Kontsevich' star product.
- The relation of our construction with Drinfeld twists (see, e.g. , [5, 33]), as well as with the interesting construction in [7].

We plan on elucidating at least some of these in the near future.

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A. Proofs

We give in this appendix various proofs that use in an essential way Hopf algebra techniques, familiarity with which is assumed. To establish the notation, we start by collecting some standard facts — [34] is an appropriate reference.

The action $g(\partial_z) \triangleright f(z)$ that appears in (2.15), is given by

$$g(\partial_z) \triangleright f(z) = f_{(1)} \langle g, f_{(2)} \rangle = f_{(2)} \langle g, f_{(1)} \rangle , \quad (\text{A.1})$$

where $\Delta(f)$ is the coproduct inferred from the primitive one of the z 's, eq. (2.19), and

$$\langle g(\partial_z), f(z) \rangle = g(\partial_z) \triangleright f(z)|_{z=0} . \quad (\text{A.2})$$

The commutation relations between g and f above can be written as

$$g(\partial_z)f(z) = (g_{(1)}(\partial_z) \triangleright f(z)) g_{(2)}(\partial_z) = f_{(1)} \langle g_{(1)}, f_{(2)} \rangle g_{(2)} . \quad (\text{A.3})$$

We use the standard Sweedler notation for the coproduct of $\psi(\zeta) \in \mathcal{A}$, where \mathcal{A} is the algebra of functions on the group manifold,

$$\Delta(\psi(\zeta)) = \psi_{(1)}(\zeta) \otimes \psi_{(2)}(\zeta) \quad (\text{A.4})$$

(the use of the same symbol Δ as for the coproduct in \mathcal{F} should cause no confusion as the nature of the map can be inferred from that of its argument). The semidirect product commutation relations with the LIVF Z are given by

$$Z\psi = \psi_{(1)} \langle Z_{(1)}, \psi_{(2)} \rangle Z_{(2)}, \quad (\text{A.5})$$

where $\Delta(Z)$ is the primitive one, and the inner product $\langle \cdot, \cdot \rangle : \mathfrak{g} \otimes \mathcal{A} \rightarrow \mathbb{R}$ is defined by

$$\langle Z_A, \psi(\zeta) \rangle = \left. \frac{\partial \psi(\zeta)}{\partial \zeta^A} \right|_{\zeta=0}. \quad (\text{A.6})$$

Eq. (A.5) can be extended from $\mathfrak{g} \otimes \mathcal{A}$ to $\hat{\mathcal{F}} \otimes \mathcal{A}$ by multiplicativity and linearity of $\hat{\Delta}$, and the relation

$$\langle XY, \psi \rangle = \langle X, \psi_{(1)} \rangle \langle Y, \psi_{(2)} \rangle, \quad (\text{A.7})$$

with X, Y in $\hat{\mathcal{F}}$.

The *left adjoint action* $\blacktriangleright : \hat{\mathcal{F}} \otimes \hat{\mathcal{F}} \rightarrow \hat{\mathcal{F}}$, defined on $\mathfrak{g} \otimes \mathfrak{g}$ by

$$Z_A \blacktriangleright Z_B = f_{AB}{}^C Z_C, \quad (\text{A.8})$$

is extended to $\hat{\mathcal{F}} \otimes \hat{\mathcal{F}}$ by linearity in both arguments and the relations

$$(XY) \blacktriangleright V = X \blacktriangleright (Y \blacktriangleright V), \quad X \blacktriangleright (YV) = (X_{(1)} \blacktriangleright Y)(X_{(2)} \blacktriangleright V). \quad (\text{A.9})$$

The *right adjoint coaction*

$$\Delta_{\mathcal{A}} : \hat{\mathcal{F}} \rightarrow \hat{\mathcal{F}} \otimes \mathcal{A}, \quad X \mapsto \Delta_{\mathcal{A}}(X) \equiv X^{(1)} \otimes X^{(2)'}, \quad (\text{A.10})$$

is dual to the adjoint action \blacktriangleright , in the sense that

$$X \blacktriangleright Y = Y^{(1)} \langle X, Y^{(2)'} \rangle, \quad (\text{A.11})$$

and satisfies dualized versions of (A.9),

$$(\Delta_{\mathcal{A}} \otimes \text{id})\Delta_{\mathcal{A}} = (\text{id} \otimes \Delta)\Delta_{\mathcal{A}}, \quad \Delta_{\mathcal{A}}(XY) = \Delta_{\mathcal{A}}(X)\Delta_{\mathcal{A}}(Y). \quad (\text{A.12})$$

Putting $\Delta_{\mathcal{A}}(Z_B) \equiv Z_C \otimes M^C{}_B$ one obtains

$$\langle Z_A, M^C{}_B \rangle = f_{AB}{}^C. \quad (\text{A.13})$$

It also holds

$$\epsilon(M^A{}_B) \equiv \langle 1, M^A{}_B \rangle = \delta^A{}_B. \quad (\text{A.14})$$

The commutation relations in $\hat{\mathcal{F}}$ are given by

$$XY = (X_{(1)} \blacktriangleright Y)X_{(2)} = Y^{(1)} \langle X_{(1)}, Y^{(2)'} \rangle X_{(2)}. \quad (\text{A.15})$$

Proposition 4.

Proof. The proof goes by induction. Since $\omega(Z_A) = \partial_A$, it is trivial to check that the property holds for \hat{z}_A . Next, assume that it is true for $\hat{f}(\hat{z})$, a polynomial of order n in the \hat{z}_A , and consider the polynomial of order $n+1$, $\hat{f}(\hat{z})\hat{z}_A$.

On one hand,

$$\begin{aligned}
 \Omega\left(\hat{f}(\hat{z})\hat{z}_A\right) &\stackrel{(2.12)}{=} \omega\left(\hat{f}(Z)Z_A\right) \\
 &\stackrel{(2.13)}{=} \omega\left(f(z)Z_A\right) \\
 &\stackrel{(2.2)}{=} \omega\left(f(z)\psi_A^B z_B\right) \\
 &\stackrel{(A.3)}{=} \omega\left(\psi_A^B{}_{(1)}\left\langle f_{(1)}, \psi_A^B{}_{(2)}\right\rangle f_{(2)}z_B\right) \\
 &\stackrel{(2.11)}{=} \epsilon(\psi_A^B{}_{(1)})\left\langle f_{(1)}, \psi_A^B{}_{(2)}\right\rangle f_{(2)}z_B \\
 &= \left\langle f_{(1)}, \psi_A^B\right\rangle f_{(2)}z_B,
 \end{aligned}$$

so that

$$\begin{aligned}
 \Delta\left(\Omega(\hat{f}(\hat{z})\hat{z}_A)\right) &= \left\langle f_{(1)}, \psi_A^B\right\rangle (f_{(2)}z_{B(1)} \otimes f_{(3)}z_{B(2)}) \\
 &\stackrel{(2.19)}{=} \left\langle f_{(1)}, \psi_A^B\right\rangle (f_{(2)}z_B \otimes f_{(3)} + f_{(2)} \otimes f_{(3)}z_B).
 \end{aligned} \tag{A.16}$$

On the other hand,

$$\begin{aligned}
 (\Omega \otimes \Omega)\hat{\Delta}\left(\hat{f}(\hat{z})\hat{z}_A\right) &\stackrel{(2.12)}{=} (\omega \otimes \omega)\left(\hat{f}_{(1)}(Z)Z_A \otimes \hat{f}_{(2)}(Z) + \hat{f}_{(1)}(Z) \otimes \hat{f}_{(2)}(Z)Z_A\right) \\
 &\stackrel{(2.13)}{=} (\omega \otimes \omega)\left(\omega(\hat{f}_{(1)}(Z))Z_A \otimes \hat{f}_{(2)}(Z) + \hat{f}_{(1)}(Z) \otimes \omega(\hat{f}_{(2)}(Z))Z_A\right) \\
 &= (\omega \otimes \omega)\left(f_{(1)}(z)Z_A \otimes f_{(2)}(z) + f_{(1)}(z) \otimes f_{(2)}(z)Z_A\right) \\
 &\stackrel{(A.1)}{=} \left\langle f_{(1)}, \psi_A^B\right\rangle f_{(2)}z_B \otimes f_{(3)} + f_{(1)} \otimes \left\langle f_{(2)}, \psi_A^B\right\rangle f_{(3)}z_B,
 \end{aligned} \tag{A.17}$$

where the third equality used the induction hypothesis. The proposition now follows by comparison of (A.16), (A.17), and the coassociativity of the coproduct. \square

Proposition 7.

Proof. We first show that

$$\llbracket \hat{f}\hat{g} \rrbracket = \llbracket K(\hat{g})\hat{f} \rrbracket, \tag{A.18}$$

where

$$K(\hat{g}) \equiv \left\langle S(\hat{g}^{(1)}{}_{(1)}), \hat{g}^{(2)'} \right\rangle \hat{g}^{(1)}{}_{(2)}, \tag{A.19}$$

with S denoting the antipode and $\hat{g}^{(1)}{}_{(1)} \otimes \hat{g}^{(1)}{}_{(2)} \otimes \hat{g}^{(2)'} \equiv (\Delta \otimes \text{id})\Delta_{\mathcal{A}}(\hat{g})$. Indeed,

$$\begin{aligned}
 \llbracket \hat{f}\hat{g} \rrbracket &\stackrel{(A.15)}{=} \left\langle \hat{f}_{(1)}, \hat{g}^{(2)'} \right\rangle \llbracket \hat{g}^{(1)}\hat{f}_{(2)} \rrbracket \\
 &= \left\langle \hat{f}_{(1)}S(\hat{f}_{(2)})S(\hat{g}^{(1)}{}_{(1)}), \hat{g}^{(2)'} \right\rangle \llbracket \hat{g}^{(1)}{}_{(2)}\hat{f}_{(3)} \rrbracket \\
 &= \left\langle S(\hat{g}^{(1)}{}_{(1)}), \hat{g}^{(2)'} \right\rangle \llbracket \hat{g}^{(1)}{}_{(2)}\hat{f} \rrbracket,
 \end{aligned} \tag{A.20}$$

where in the second line, we used the invariance of the integral to multiply $\hat{f}_{(1)}$ from the right by $S(1)$. By repeated application of (A.18), the multiplicativity of K is established,³ so, given its obvious linearity, it suffices to compute it for the generators Z_A . We find

$$(\Delta \otimes \text{id})\Delta_{\mathcal{A}}(Z_A) = \Delta(Z_B) \otimes M^B_A = Z_B \otimes 1 \otimes M^B_A + 1 \otimes Z_B \otimes M^B_A, \quad (\text{A.21})$$

so that

$$\begin{aligned} K(Z_A) &= \langle -Z_B, M^B_A \rangle 1 + \langle 1, M^B_A \rangle Z_B \\ &\stackrel{(\text{A.14})}{=} Z_A - \langle Z_B, M^B_A \rangle \\ &\stackrel{(\text{A.13})}{=} Z_A - f_{BA}^B \\ &= Z_A + c_A, \end{aligned} \quad (\text{A.22})$$

implying $K(\hat{g}(Z)) = \hat{g}(Z + c)$. \square

Eq. (3.9).

Proof. The Hopf algebras \mathcal{R} , of functions on the real line, with coordinate x , and \mathcal{P} , of functions of ∂_x , both equipped with the standard Hopf structure, are dually paired, via the inner product

$$\langle \partial_x, x \rangle = 1, \quad (\text{A.23})$$

extended to $\mathcal{P} \otimes \mathcal{R}$ in the standard fashion,

$$\langle g(\partial_x), f(x) \rangle = (g(\partial_x) \triangleright f(x))_{x=0}. \quad (\text{A.24})$$

It is easily established that $\{x^n\}$, $\{\frac{1}{n!}\partial_x^n\}$, are dual bases, and so are $\{x^{(n)}\}$, $\{\frac{1}{n!}D_x^n\}$, where $x^{(n)} = x(x-1)\dots(x-(n-1))$, and $D_x \triangleright f(x) = f(x+1) - f(x) = (e^{\partial_x} - 1) \triangleright f$. The desired identity then follows from the invariance of the canonical element C under linear change of bases,

$$\begin{aligned} C &= \sum_{n=0}^{\infty} \frac{1}{n!} x^n \otimes \partial_x^n \\ &= e^{x \otimes \partial_x} \\ &= \sum_{n=0}^{\infty} \frac{1}{n!} x^{(n)} \otimes D_x^n \\ &= \sum_{n=0}^{\infty} \frac{1}{n!} x^{(n)} \otimes (e^{\partial_x} - 1)^n, \end{aligned} \quad (\text{A.25})$$

with the identification $x \otimes 1 \mapsto z$, $1 \otimes \partial_x \mapsto a$. \square

B. Further examples

We present two more examples dealing with integration in κ -Minkowski spacetime.

³Direct proof of the multiplicativity of K from its definition, eq. (A.19), is left as a non-trivial exercise for the reader (*Hint*: the Jacobi identity is needed).

Example 2. In the context of Ex. 3.1.2, let $\hat{G} = e^{-\hat{x}^2} e^{-\hat{t}^2} \hat{x}^m$. Then, some straightforward algebra gives

$$\begin{aligned}
 \Omega(\hat{G}) &= e^{-x^2} x^m e^{-(t+m\lambda)^2} \\
 \llbracket \hat{G} \rrbracket &= \pi \left(\partial_r^m \triangleright e^{\frac{r^2}{4}} \right)_{r=0} \\
 \Delta(\hat{G}) &= \sum_{k=0}^m \sum_{a=0}^{\infty} \sum_{b=0}^{\infty} \binom{m}{k} \frac{(-2)^a (-2)^b}{a! b!} \left(e^{-\hat{x}^2} \hat{x}^a e^{-\hat{t}^2} \hat{t}^b \hat{x}^k \otimes e^{-\hat{x}^2} \hat{x}^a e^{-\hat{t}^2} \hat{t}^b \hat{x}^{m-k} \right) \\
 \Omega(e^{-\hat{x}^2} \hat{x}^a e^{-\hat{t}^2} \hat{t}^b \hat{x}^k) &= e^{-x^2} x^{a+k} e^{-(t+k\lambda)^2} (t+k\lambda)^b \\
 \llbracket e^{-\hat{x}^2} \hat{x}^a e^{-\hat{t}^2} \hat{t}^b \hat{x}^k \rrbracket &= \pi \left(\partial_s^{a+k} \triangleright e^{\frac{s^2}{4}} \right)_{s=0} \left(\partial_r^b \triangleright e^{\frac{r^2}{4}} \right)_{r=0} \\
 \llbracket \hat{G}_{(1)} \rrbracket \hat{G}_{(2)} &= \pi e^{-\hat{x}^2} \left(\left(e^{-2\hat{x}\partial_r} e^{-\hat{t}^2} \left(e^{-2\hat{t}\partial_s} \triangleright e^{\frac{s^2}{4}} \right)_{s=0} (\partial_r + \hat{x})^m \right) \triangleright e^{\frac{r^2}{4}} \right)_{r=0} \\
 &= \pi \left((\partial_r + \hat{x})^m \triangleright e^{\frac{r^2}{4} - r\hat{x}} \right)_{r=0} \\
 \llbracket \hat{G}_{(1)} \rrbracket G_{(2)} &= \pi \sum_{k=0}^m \binom{m}{k} e^{-(t+k\lambda)^2} \left(e^{-2(t+k\lambda)\partial_s} \triangleright e^{\frac{s^2}{4}} \right)_{s=0} \times \\
 &\quad \times e^{-x^2} \left(x^{m-k} \partial_r^k e^{-2x\partial_r} \triangleright e^{\frac{r^2}{4}} \right)_{r=0} \\
 &= \pi \left((\partial_r + x)^m \triangleright e^{\frac{r^2}{4} - rx} \right)_{r=0}.
 \end{aligned}$$

However, one easily computes

$$\begin{aligned}
 \left((\partial_r + c)^m \triangleright e^{\frac{r^2}{4} - rc} \right)_{r=0} &= \sum_{k=0}^m \binom{m}{k} c^{m-k} \left(\partial_r^k \triangleright e^{\frac{r^2}{4}} e^{-rc} \right)_{r=0} \\
 &= \sum_{k=0}^m \sum_{l=0}^k \binom{m}{k} \binom{k}{l} c^{m-k} \left(\partial_r^l \triangleright e^{\frac{r^2}{4}} \right)_{r=0} \left(\partial_r^{k-l} \triangleright e^{-rc} \right)_{r=0} \\
 &= \sum_{k=0}^m \sum_{l=0}^k \binom{m}{k} \binom{k}{l} c^{m-k} (-c)^{k-l} \left(\partial_r^l \triangleright e^{\frac{r^2}{4}} \right)_{r=0} \\
 &= \sum_{k=0}^m \binom{m}{k} c^{m-k} \left((\partial_r - c)^k \triangleright e^{\frac{r^2}{4}} \right)_{r=0} \\
 &= \left(\partial_r^m \triangleright e^{\frac{r^2}{4}} \right)_{r=0},
 \end{aligned}$$

so that

$$\llbracket \hat{G} \rrbracket = \llbracket \hat{G}_{(1)} \rrbracket \hat{G}_{(2)} = \llbracket \hat{G}_{(1)} \rrbracket G_{(2)} = \pi \left(\partial_r^m \triangleright e^{\frac{r^2}{4}} \right)_{r=0}.$$

Consider also the integral

$$\begin{aligned}\llbracket \hat{G}(\hat{x} + \lambda c_x, \hat{t} + \lambda c_t) \rrbracket &= \llbracket e^{-\hat{x}^2} e^{-(\hat{t}+\lambda)^2} \hat{x}^m \rrbracket \\ &= \int e^{-x^2} x^m e^{-(t+\lambda+m\lambda)^2} \\ &= \pi \left(\partial_r^m \triangleright e^{\frac{r^2}{4}} \right)_{r=0},\end{aligned}$$

showing that $\llbracket \hat{G}(\hat{z}) \rrbracket = \llbracket \hat{G}(\hat{z} + \lambda c) \rrbracket$. Finally, if we write $\hat{G} = \hat{g} \hat{h}$ with $\hat{g} = e^{-\hat{x}^2} e^{-\hat{t}^2}$ and $\hat{h} = \hat{x}^m$, and compute

$$\begin{aligned}\llbracket \hat{h}(\hat{x}, \hat{t}) \hat{g}(\hat{x} - \lambda c_x, \hat{t} - \lambda c_t) \rrbracket &= \llbracket \hat{x}^m e^{-\hat{x}^2} e^{-(\hat{t}-\lambda)^2} \rrbracket = \int x^m e^{-x^2} e^{-(t-\lambda)^2} \\ &= \pi \left(\partial_r^m \triangleright e^{\frac{r^2}{4}} \right)_{r=0},\end{aligned}$$

we obtain, $\llbracket \hat{g}(\hat{z}) \hat{h}(\hat{z}) \rrbracket = \llbracket \hat{h}(\hat{z}) \hat{g}(\hat{z} - \lambda c) \rrbracket$.

Example 3. Consider the function $\hat{H}(\hat{x}, \hat{t}) = e^{-\hat{x}^2} e^{-\hat{t}^2} \hat{x}^m e^{\alpha \hat{t}}$, with

$$\begin{aligned}\llbracket \hat{H}(\hat{x}, \hat{t}) \rrbracket &= \llbracket e^{-\hat{x}^2} e^{-\hat{t}^2} \hat{x}^m e^{\alpha \hat{t}} \rrbracket \\ &= \int e^{-x^2} x^m e^{-(t+m\lambda)^2} e^{\alpha t} \\ &= \left(\int x^m e^{-x^2} \right) \sqrt{\pi} e^{\frac{\alpha^2}{2}} e^{-\alpha m \lambda}.\end{aligned}$$

Now write $\hat{H} = \hat{g} \hat{k}$, with $\hat{g} = e^{-\hat{x}^2} e^{-\hat{t}^2}$ and $\hat{k} = \hat{x}^m e^{\alpha \hat{t}}$, and compute the integral

$$\begin{aligned}\llbracket \hat{k}(\hat{x}, \hat{t}) \hat{g}(\hat{x} - \lambda c_x, \hat{t} - \lambda c_t) \rrbracket &= \llbracket \hat{x}^m e^{\alpha \hat{t}} e^{-\hat{x}^2} e^{-(\hat{t}-\lambda)^2} \rrbracket \\ &= \int x^m e^{-e^{2\alpha\lambda} x^2} e^{\alpha t} e^{-(t-\lambda)^2} \\ &= e^{-\alpha\lambda(m+1)} \int x^m e^{-x^2} e^{\alpha t} e^{-(t-\lambda)^2} \\ &= \left(\int x^m e^{-x^2} \right) \sqrt{\pi} e^{\frac{\alpha^2}{2}} e^{-\alpha m \lambda}.\end{aligned}$$

Once again, $\llbracket \hat{g}(\hat{z}) \hat{k}(\hat{z}) \rrbracket = \llbracket \hat{k}(\hat{z}) \hat{g}(\hat{z} - \lambda c) \rrbracket$. Similarly

$$\begin{aligned}\llbracket \hat{k}(\hat{x} + \lambda c_x, \hat{t} + \lambda c_t) \hat{g}(\hat{x}, \hat{t}) \rrbracket &= \llbracket \hat{x}^m e^{\alpha(\hat{t}+\lambda)} e^{-\hat{x}^2} e^{-\hat{t}^2} \rrbracket \\ &= \int x^m e^{-e^{2\alpha\lambda} x^2} e^{\alpha(t+\lambda)} e^{-t^2} \\ &= e^{-\alpha m \lambda} \int x^m e^{-x^2} e^{\alpha t} e^{-t^2} \\ &= \left(\int x^m e^{-x^2} \right) \sqrt{\pi} e^{\frac{\alpha^2}{2}} e^{-\alpha m \lambda},\end{aligned}$$

so $\llbracket \hat{g}(\hat{z}) \hat{k}(\hat{z}) \rrbracket = \llbracket \hat{k}(\hat{z} + \lambda c) \hat{g}(\hat{z}) \rrbracket$.

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